

# The Treewidth-Convex Hull Theorem and DP for Cut Generation in MINLP

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## Summary

We provide an alternative proof for tree-width convex hull theorem. Next, in a column generation setting, we use dynamic programming to solve pricing problem for solving cut generating problems for non-linear problems with multilinear intermediates.

## Unconstrained Binary Problem

$$\min_{\mathbf{b} \in \{0,1\}^n} \sum_{T \subseteq N} c_T \prod_{i \in T} b_i,$$

Unconstrained binary optimization has many applications ranging from finance, communication, theoretical physics to economics and machine learning.

## Graph and Tree-Decomposition

$$\min b_1 b_2 b_3 - 4b_2 b_3 b_4 b_5 + 2b_2 b_5 + 4b_3 b_6$$

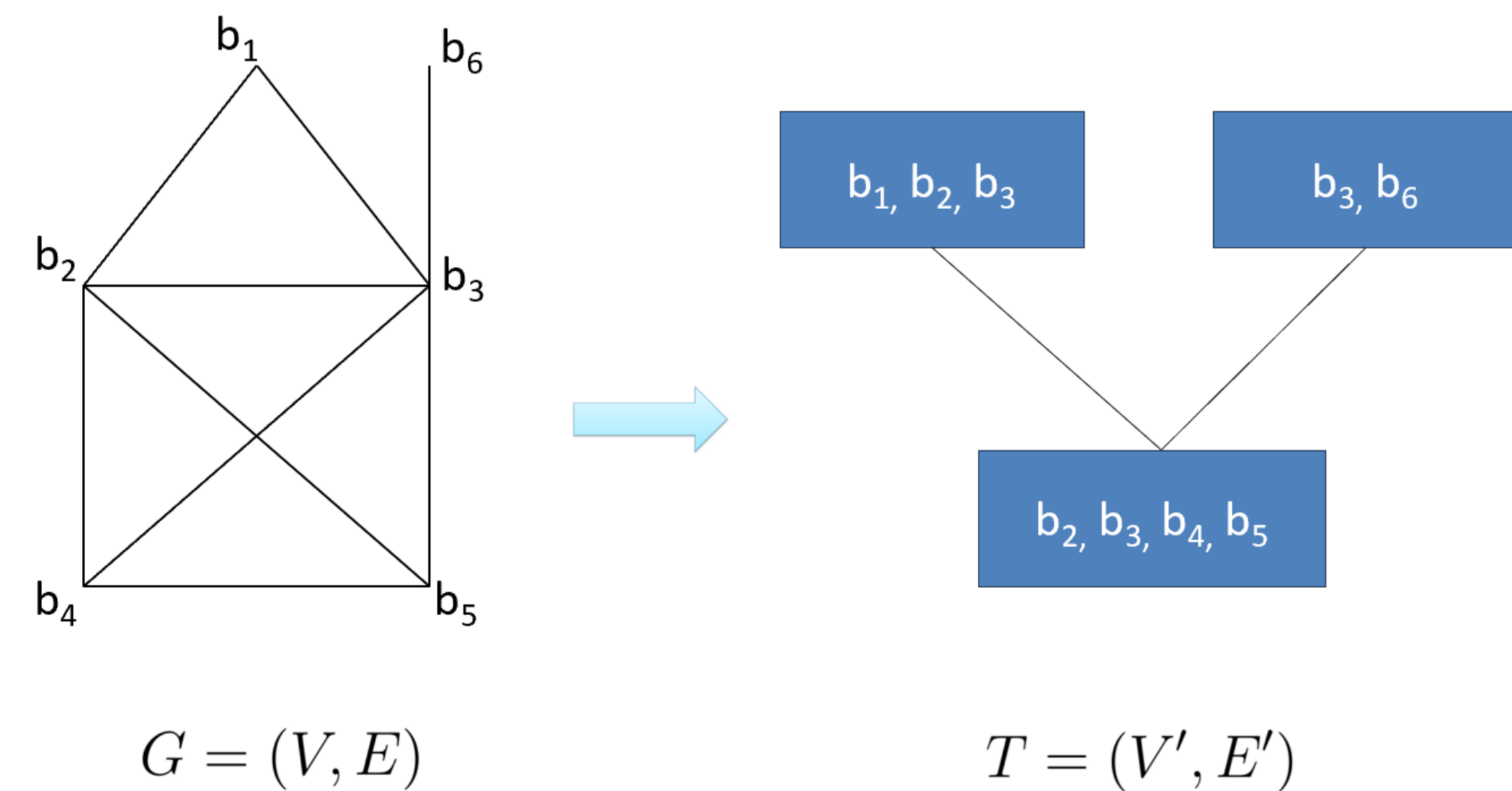


Figure 1. Tree-decomposition of a graph

## Resulting Simplification

- **Theorem:** Consider an UBP with treewidth  $d$  and number of variables  $n$ . This problem can be reframed as an LP with  $O(n2^d)$  nonnegative variables and constraints. [2].
- **Contribution:** We show that the LP can be converted into a DP formulation and hence the integrality can be proven. A corollary is that the LP is Totally Dual Integral (TDI).

## Multilinear Intermediates and Adding Cuts

- Next, consider a multilinear intermediate

$$z = L(x) = \sum_{T \subseteq N} c_T \prod_{i \in T} x_i$$

where  $N = \{1, 2, 3, \dots, n\}$  which is defined over a box  $\mathcal{H} = \prod_{j=1}^n [l_j, u_j]$ .

- Given a relaxation solution  $(x^*, z^*)$ , the dual to cut generation LP is: [1]:

$$\begin{aligned} \min_{\lambda} \quad & \sum_{i \in I} \lambda_i L(v^i) \\ & \sum_{i \in I} \lambda_i v^i = x^* \\ & \sum_{i \in I} \lambda_i = 1 \\ & \lambda_i \geq 0 \end{aligned}$$

- Let  $a \in R^n$  and  $b \in R$  be the dual optimal to the first and second constraints. We add the cut  $z \geq ax + b$  if  $z^* < ax^* + b$ .

## The Framework

- We propose a column generation strategy to solve the dual to cut generation LP.
- Proposed DP strategy for pricing: Solve the unconstrained binary problem  $L(\mathbf{b}) - \pi^T \mathbf{b} - \pi_0$  using dynamic programming.

## Computational Results

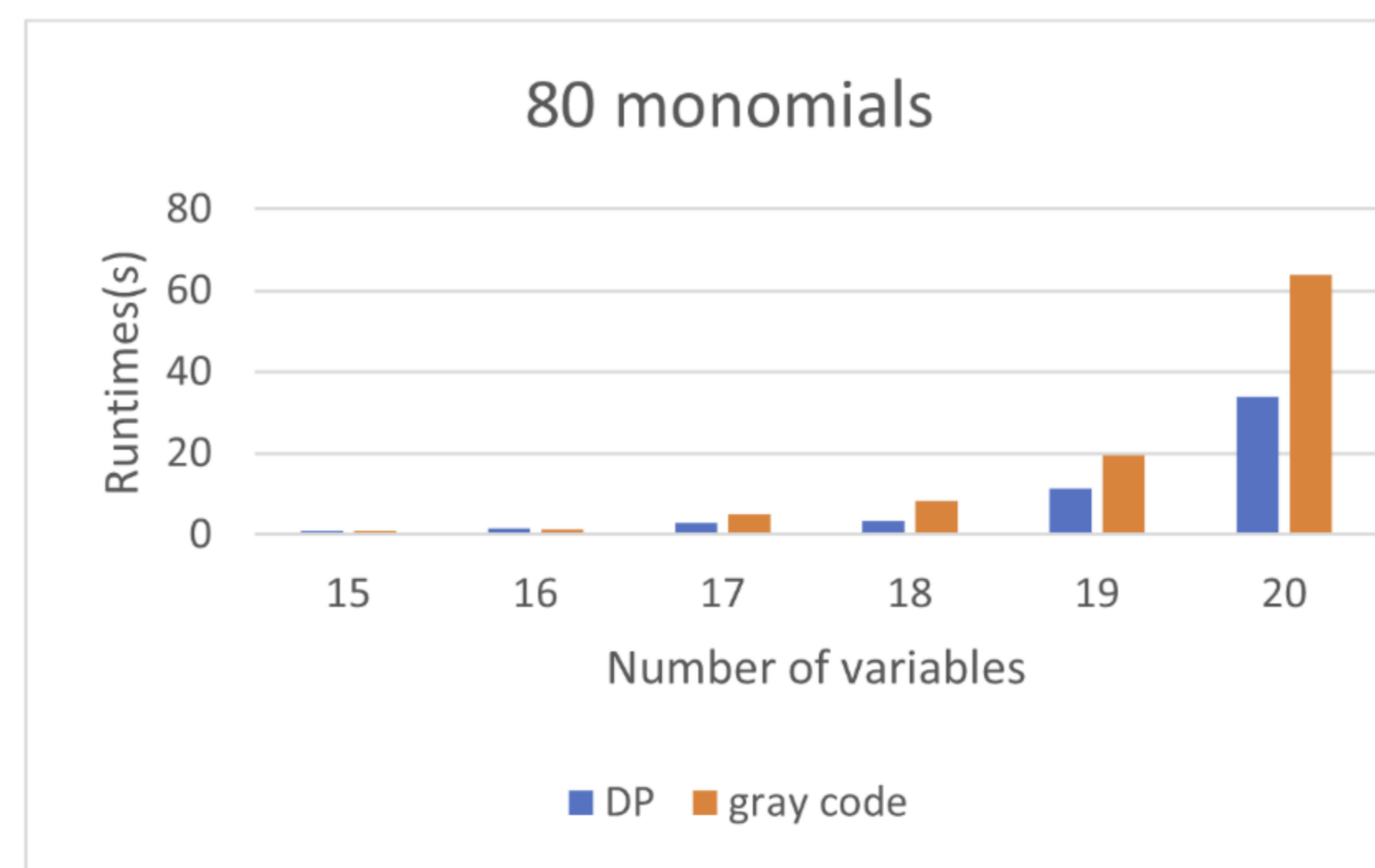
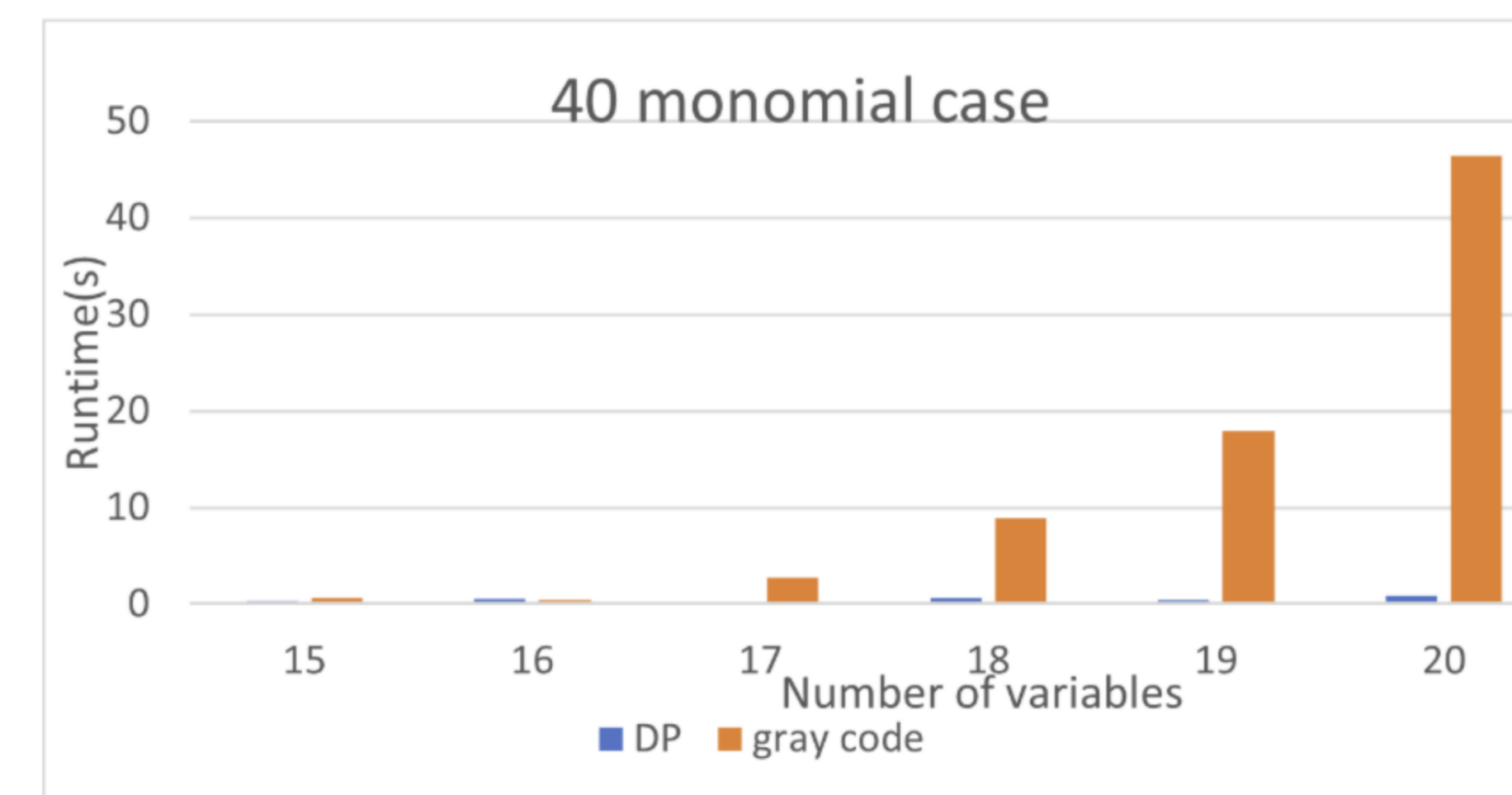


Figure 2. Comparison of time taken to solve CGLP

## Example instances

$n$	$d$	Basic relaxation with our cuts	Time(s) to add cuts	BARON LB (20 min)	Better by
<b>Type1<sup>a</sup></b>					
25	10	-14804	95	-42949	65.5%
26	10	-15622	111	-40100	61.0%
27	10	-16852	140	-47023	64.2%
28	10	-17862	149	-45524	60.8%
29	10	-18560	169	-56249	67.0%
30	10	-20286	184	-58543	65.3%
<b>Type2<sup>b</sup></b>					
25	10	-12682	76	-23246	45.4%
26	10	-13481	93	-24864	45.8%
27	10	-14178	111	-26130	45.7%
28	10	-14973	124	-26358	43.2%
29	10	-15733	163	-30518	48.4%
30	10	-16506	163	-33234	50.3%

<sup>a</sup> Unconstrained NLP.

<sup>b</sup> Linearly constrained NLP.

\* Instances generated from a known tree-decomposition.

## Conclusion and Future Direction

We proposed a new proof for treewidth convex hull theorem and a framework for solving CGLP in NLPs. Future work involves integrating this within the Branch and Bound (B&B) tree of standard solvers.

## References

- [1] Xiaowei Bao, Aida Khajavirad, Nikolaos V Sahinidis, and Mohit Tawarmalani. Global optimization of nonconvex problems with multilinear intermediates. *Mathematical Programming Computation*, 7(1):1–37, 2015.
- [2] Daniel Bienstock and Gonzalo Muñoz. LP formulations for polynomial optimization problems. *SIAM Journal on Optimization*, 28(2):1121–1150, 2018.